

# **Shallow Neural Network**

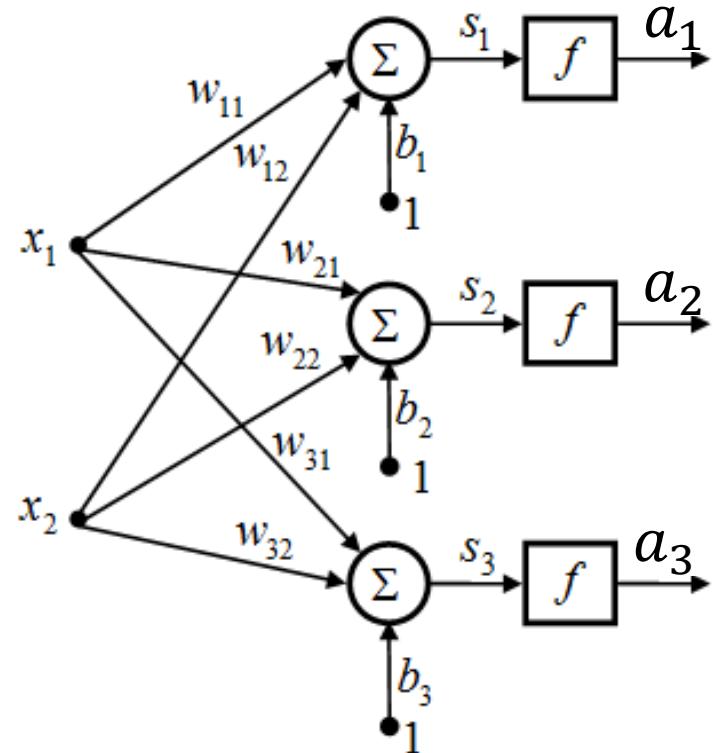
## **(Small-size, standard ANN)**

# 1 layer ANN

## 2 inputs, 3 outputs

$$x = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad W = \begin{bmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \\ w_{31} & w_{32} \end{bmatrix}$$

$$b = \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix} \quad s = \begin{bmatrix} s_1 \\ s_2 \\ s_3 \end{bmatrix} \quad a = \begin{bmatrix} a_1 \\ a_2 \\ a_3 \end{bmatrix}$$



$$s = Wx + b$$

$$\begin{bmatrix} s_1 \\ s_2 \\ s_3 \end{bmatrix} = \begin{bmatrix} w_{11} & w_{12} \\ w_{21} & w_{22} \\ w_{31} & w_{32} \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} + \begin{bmatrix} b_1 \\ b_2 \\ b_3 \end{bmatrix}$$

$$a = f(s)$$



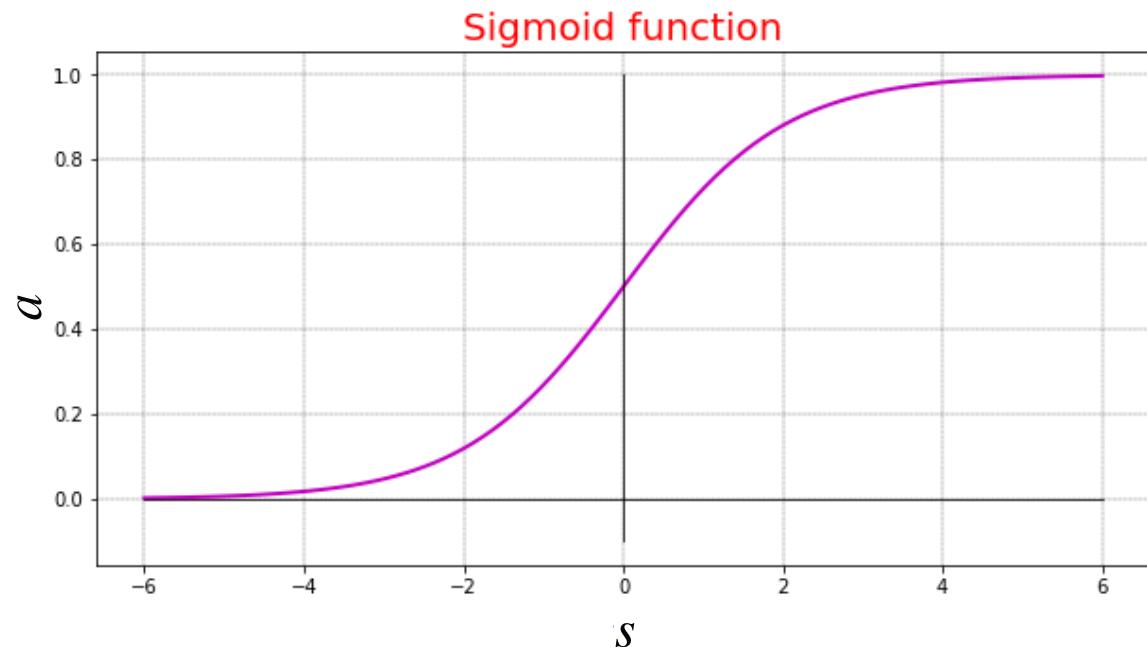
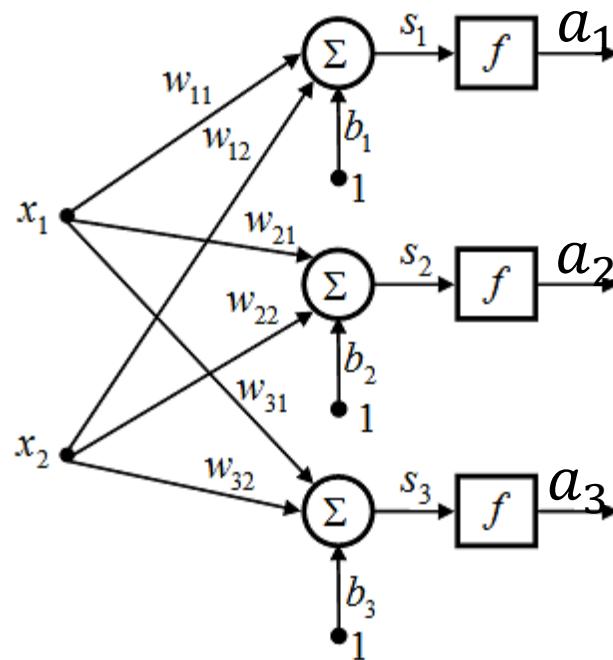
# Exercise

$$x^{(1)} = \begin{bmatrix} -1 \\ -4 \end{bmatrix} \quad x^{(2)} = \begin{bmatrix} 2 \\ 4 \end{bmatrix} \quad x^{(3)} = \begin{bmatrix} 10 \\ 0 \end{bmatrix}$$

$$W = \begin{bmatrix} -0.5 & -1 \\ -0.1 & 1 \\ 0.75 & -0.5 \end{bmatrix} \quad b = \begin{bmatrix} 0.5 \\ -0.5 \\ -3 \end{bmatrix}$$

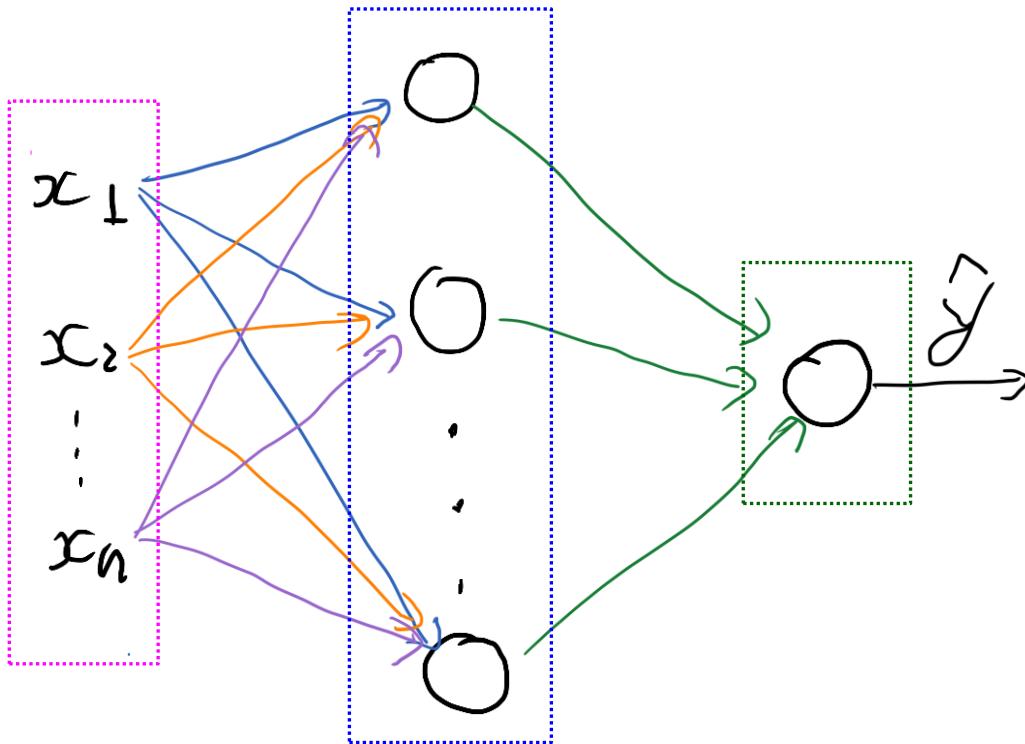
$$f(s) = \frac{1}{1 + e^{-s}}$$

Compute the output vector  $a$ ,  
for each input vector  $x^{(i)}$



# Neural network representation

## 2- layer NN

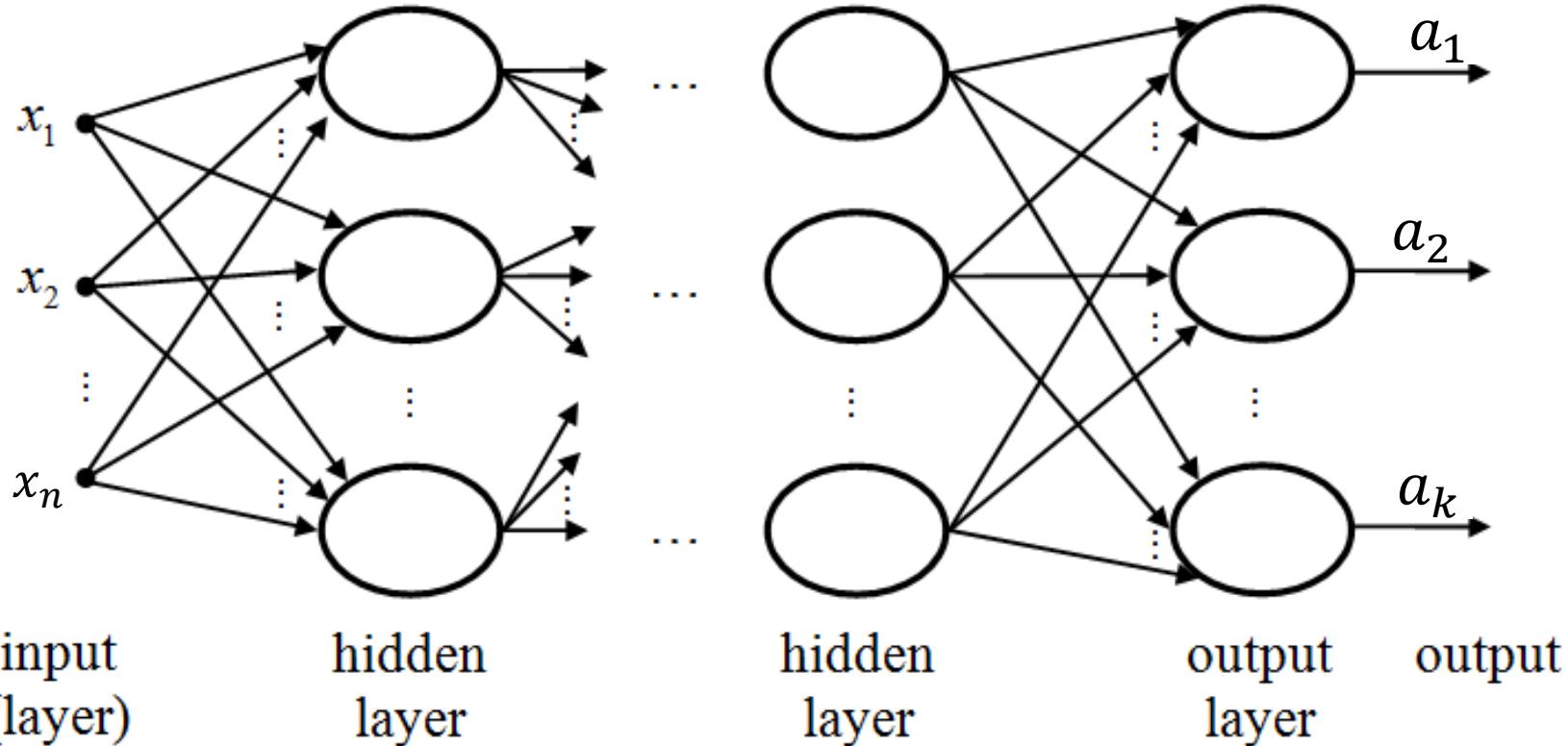


Input

Hidden layer  
1<sup>st</sup> layer

Output layer  
2<sup>nd</sup> layer

# Feedforward Neural Network



The architecture of a multilayer feedforward neural network

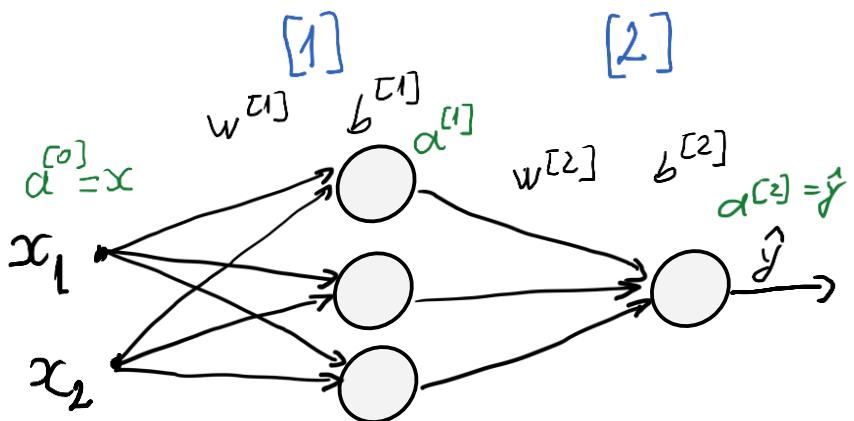
It is common for different layers to have different numbers of neurons.

**Multiple-layer networks** are quite powerful.

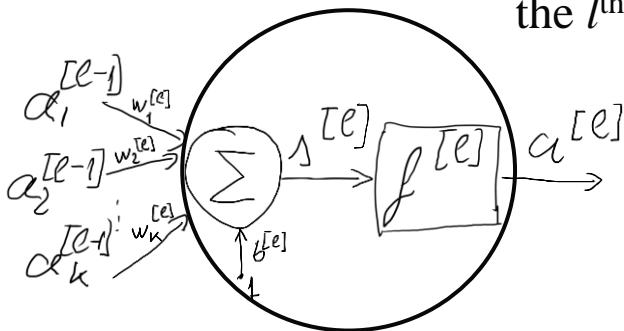
An ANN of two layers, where the first layer is sigmoid and the second layer is linear, can be trained **to approximate any function** (with a finite number of discontinuities) **arbitrarily well** - **universal approximator**

# 2-layer NN. Illustration for 2 inputs 1 output; 1 example

A neuron in the  $l^{\text{th}}$  layer



$$a^{[0]} = \begin{bmatrix} a_1^{[0]} \\ a_2^{[0]} \end{bmatrix} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \Delta^{[1]} = \begin{bmatrix} \Delta_1^{[1]} \\ \Delta_2^{[1]} \\ \Delta_3^{[1]} \end{bmatrix} \quad a^{[1]} = \begin{bmatrix} a_1^{[1]} \\ a_2^{[1]} \\ a_3^{[1]} \end{bmatrix} \quad \Delta^{[2]} = \begin{bmatrix} \Delta_1^{[2]} \\ \Delta_2^{[2]} \end{bmatrix} \quad a^{[2]} = \begin{bmatrix} a_1^{[2]} \\ a_2^{[2]} \end{bmatrix} = \hat{y}$$



$$w^{[1]} = \begin{bmatrix} w_{11}^{[1]} & w_{12}^{[1]} \\ w_{21}^{[1]} & w_{22}^{[1]} \\ w_{31}^{[1]} & w_{32}^{[1]} \end{bmatrix} \quad b^{[1]} = \begin{bmatrix} b_1^{[1]} \\ b_2^{[1]} \\ b_3^{[1]} \end{bmatrix} \quad w^{[2]} = \begin{bmatrix} w_{11}^{[2]} & w_{12}^{[2]} & w_{13}^{[2]} \end{bmatrix} \quad b^{[2]} = \begin{bmatrix} b_1^{[2]} \end{bmatrix}$$

$$\Delta^{[1]} = w^{[1]} a^{[0]} + b^{[1]}; \quad a^{[1]} = f^{[1]}(\Delta^{[1]}); \quad \Delta^{[2]} = w^{[2]} a^{[1]} + b^{[2]}; \quad a^{[2]} = \hat{y} = f^{[2]}(\Delta^{[2]})$$

$$\Delta^{[e]} = w^{[e]} a^{[e-1]} + b^{[e]}; \quad a^{[e]} = f^{[e]}(\Delta^{[e]})$$

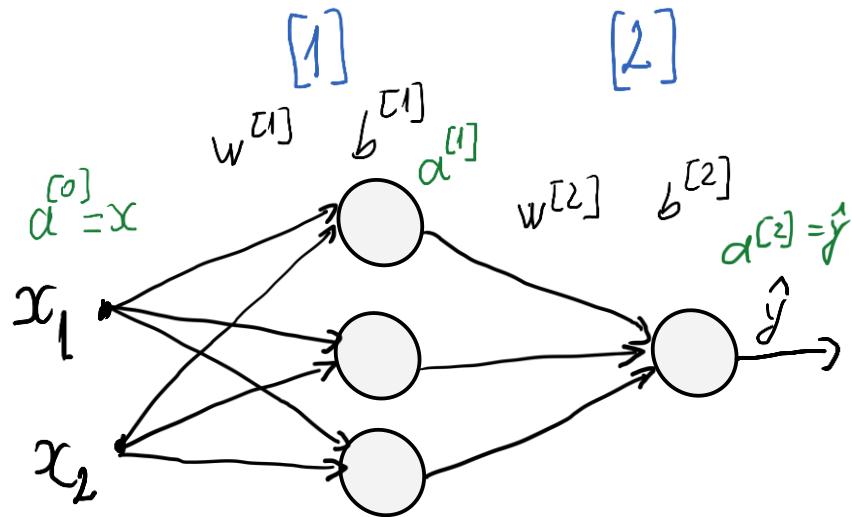
Vectorized implementation for one input example to compute the NN's output.



# Exercise

- a) Draw the schematic diagram for an ANN with:
  - 3 inputs
  - 1 hidden layer with 4 neurons
  - output layer with 2 neurons (2 outputs).
- b) Represents the vectors or matrices for the input, all intermediate variables, and the output.
- c) Represents the vectors / matrices for the training parameters in all layers.
- d) Write all the equations to compute the ANN's output.
- e) Compute the total number of training parameters

## 2-layer NN. Computing NN's output for one example.



for a single sc inspect example

$$\mathbf{z}^{[1]} = w^{[1]} \mathbf{x} + b^{[1]}$$

$$a^{[1]} = f^{[1]}(\mathbf{z}^{[1]})$$

$$\mathbf{z}^{[2]} = w^{[2]} a^{[1]} + b^{[2]}$$

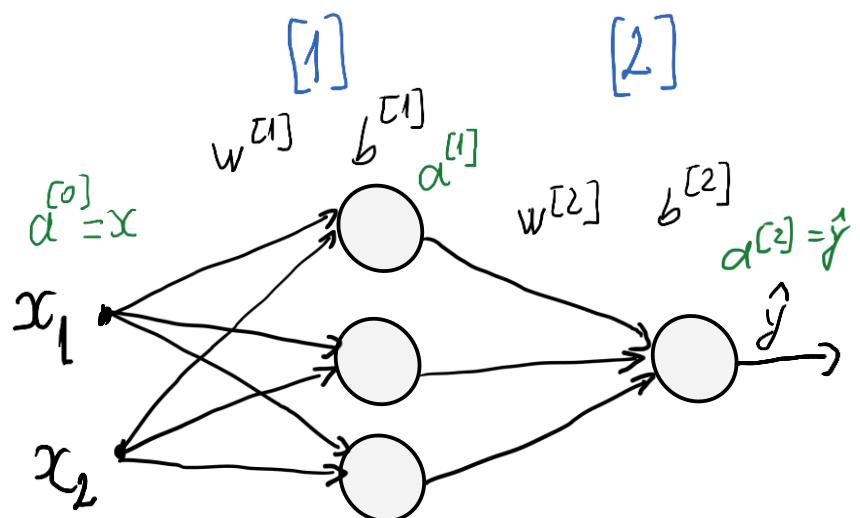
$$\hat{y} = a^{[2]} = f^{[2]}(\mathbf{z}^{[2]})$$

one example

$$\mathbf{x} = \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \quad \begin{array}{c} \uparrow \\ 2 \text{ features} \end{array}$$

$$\hat{\mathbf{y}} = [\hat{y}]$$

## 2-layer NN. Computing NN's output for multiple examples (m).



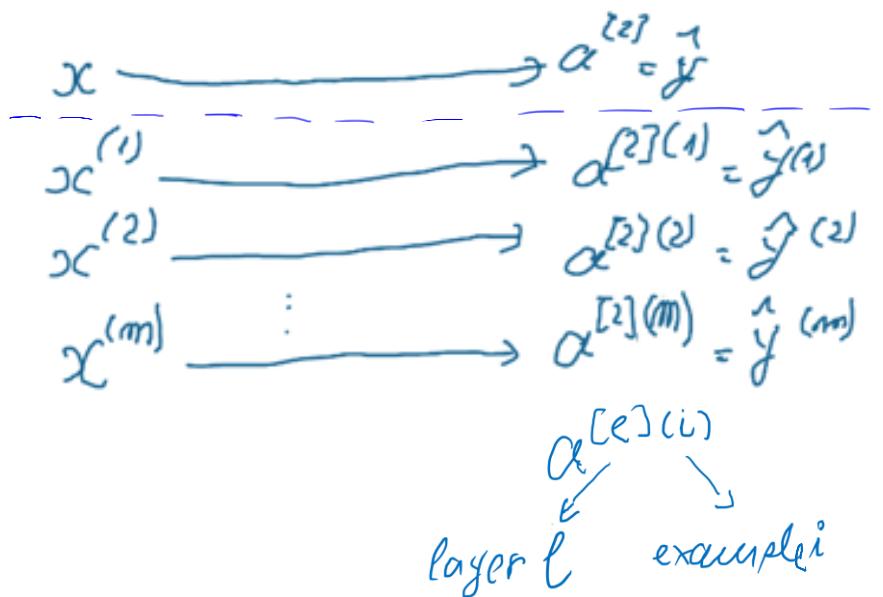
$$X = \begin{bmatrix} x_1^{(1)} & x_1^{(2)} & \dots & x_1^{(m)} \\ x_2^{(1)} & x_2^{(2)} & \dots & x_2^{(m)} \end{bmatrix}$$

$\leftarrow m \text{ examples}$

↑ 2 features

$$\hat{Y} = [\hat{y}^{(1)} \ \hat{y}^{(2)} \ \dots \ \hat{y}^{(m)}]$$

*m* input examples:



in case of multiple input examples  
*m* examples

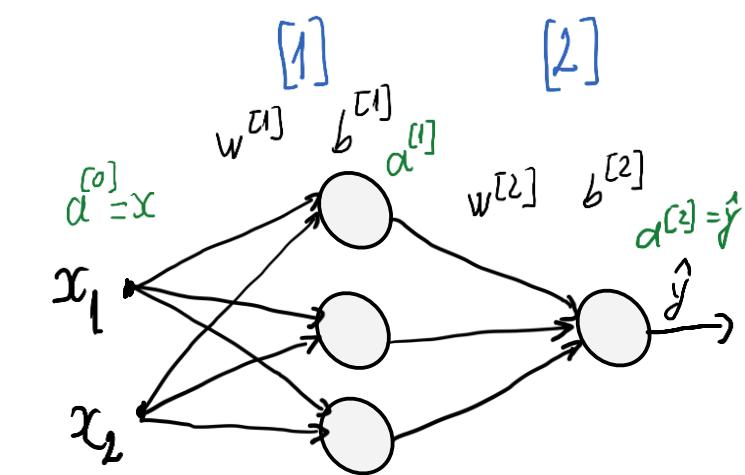
for  $i = 1 \text{ to } m$

$$\begin{aligned} \alpha^{[1](i)} &= w^{[1]} x^{(i)} + b^{[1]} \\ \alpha^{[1](i)} &= f^{[1]}(\alpha^{[1](i)}) \\ \alpha^{[2](i)} &= w^{[2]} \alpha^{[1](i)} + b^{[2]} \\ \alpha^{[2](i)} &= f^{[2]}(\alpha^{[2](i)}) \end{aligned}$$

**For loop**  
Not recommended for implementation!



## 2-layer NN. Computing NN's output for multiple examples. Vectorising across multiple examples



input

$$X = \begin{bmatrix} | & | & | \\ x^{(1)} & x^{(2)} & \dots & x^{(m)} \\ | & | & | \end{bmatrix} \quad \begin{array}{l} n^{[0]} \\ \text{f} \\ \text{e} \\ \text{a} \\ \text{t} \\ \text{u} \\ \text{r} \\ \text{e} \end{array}$$

*m examples*

$$S^{[l]} = \begin{bmatrix} | & | & | \\ s^{[l](1)} & s^{[l](2)} & \dots & s^{[l](m)} \\ | & | & | \end{bmatrix} \quad \begin{array}{l} \text{hidden} \\ \text{neurons} \\ \text{in} \\ \text{layer} \\ [l] \end{array}$$

*m examples*

$$A^{[l]} = \begin{bmatrix} | & | & | \\ a^{[l](1)} & a^{[l](2)} & \dots & a^{[l](m)} \\ | & | & | \end{bmatrix} \quad \begin{array}{l} \text{hidden} \\ \text{neurons} \\ \text{in} \\ \text{layer} \\ [l] \end{array}$$

*m examples*

$$\begin{aligned} S^{[1]} &= w^{[1]} X + b^{[1]} \\ A^{[1]} &= f^{[1]}(S^{[1]}) \\ S^{[2]} &= w^{[2]} A^{[1]} + b^{[2]} \\ \hat{y} &= A^{[2]} = f^{[2]}(S^{[2]}) \end{aligned}$$

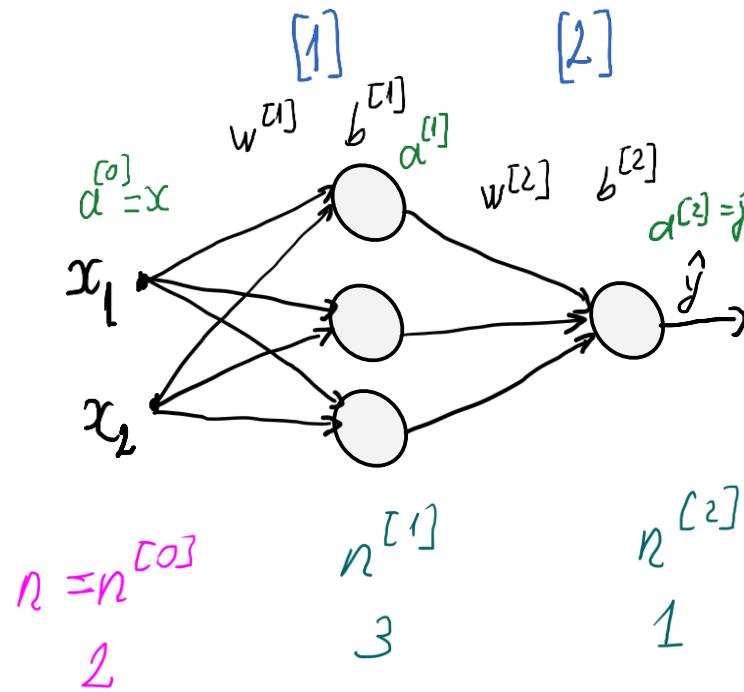
## 2-layer NN. Computing NN's output for multiple examples.

### Vectorising across multiple examples

$n = n^{[0]}$  – number of inputs (features)

$m$  – number of examples

$n^{[1]}$  – number of neurons in the (1<sup>st</sup>) hidden layer



matrix  $(n^{[1]}, m)$  matrix  $(n^{[1]}, n^{[0]})$  matrix  $(n^{[0]}, m)$  column vector  $(n^{[1]}, 1)$

$$S^{[1]} = w^{[1]}X + b^{[1]}$$
$$A^{[1]} = f^{[1]}(S^{[1]})$$

$$S^{[2]} = w^{[2]}A^{[1]} + b^{[2]}$$

$$\hat{y} = A^{[2]} = f^{[2]}(S^{[2]})$$

row vector  
 $(1, m)$

*matrix + column*  
operates correctly due  
to broadcasting

## 2-layer NN.

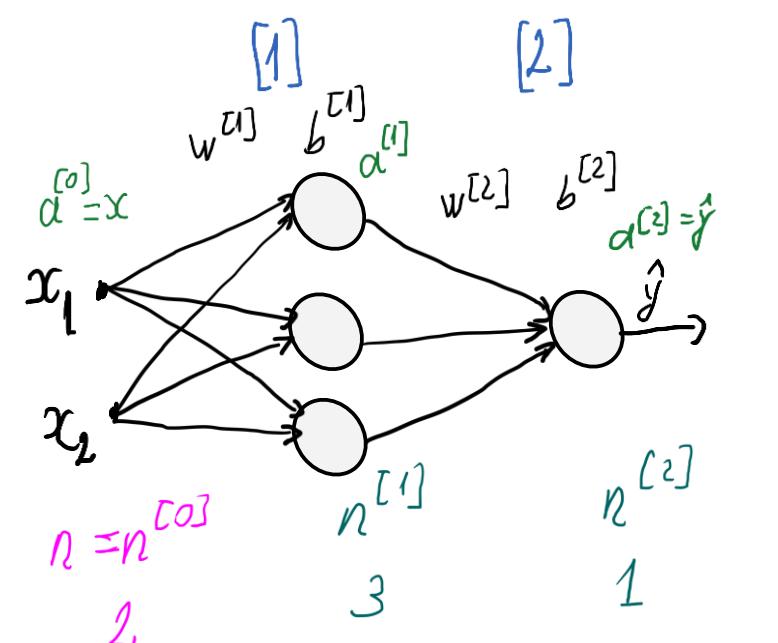
**Computing NN's output for multiple example.**

**Vectorising across multiple examples**

$n = n^{[0]}$  – number of inputs (features)

$m$  – number of examples

$n^{[1]}$  – number of neurons in the hidden layer



$$S^{[1]} = W^{[1]} \cdot X + b^{[1]}$$

$$A^{[1]} = f(S^{[1]})$$

$$S^{[2]} = W^{[2]} \cdot A^{[1]} + b^{[2]}$$

$$A^{[2]} = f(S^{[2]})$$

Annotations:  $m$  (number of examples),  $n^{[0]}$  (number of inputs/features),  $n^{[1]}$  (number of neurons in the hidden layer),  $n^{[2]}$  (number of neurons in the output layer).

# 2 - layer NN (2 inputs, 1 output). Forward and backward propagation

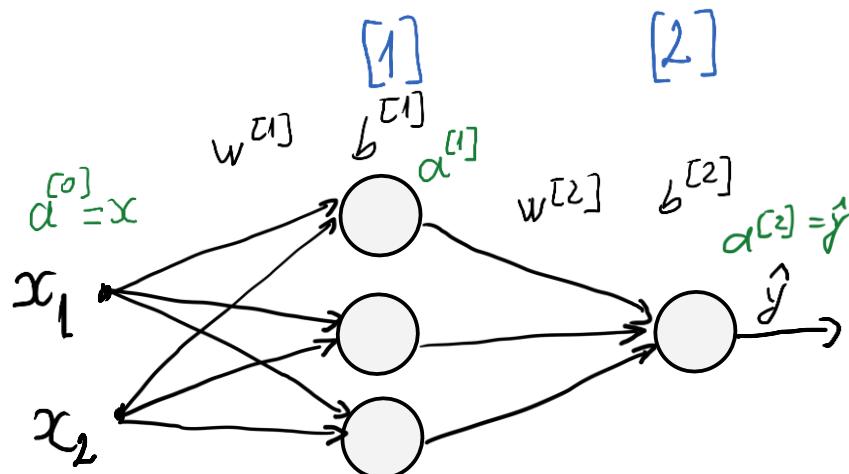
1. Compute the output - Forward propagation
2. Compute the gradients – backward propagation
3. Update the parameters

All 3 phases are necessary for ANN training:

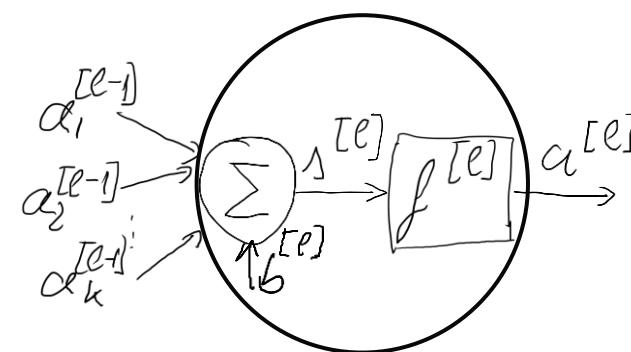
- needs multiple training examples
- multiple training epochs

For ANN simulation (inference, utilization, testing):

- only forward propagation is involved



Schematic diagram

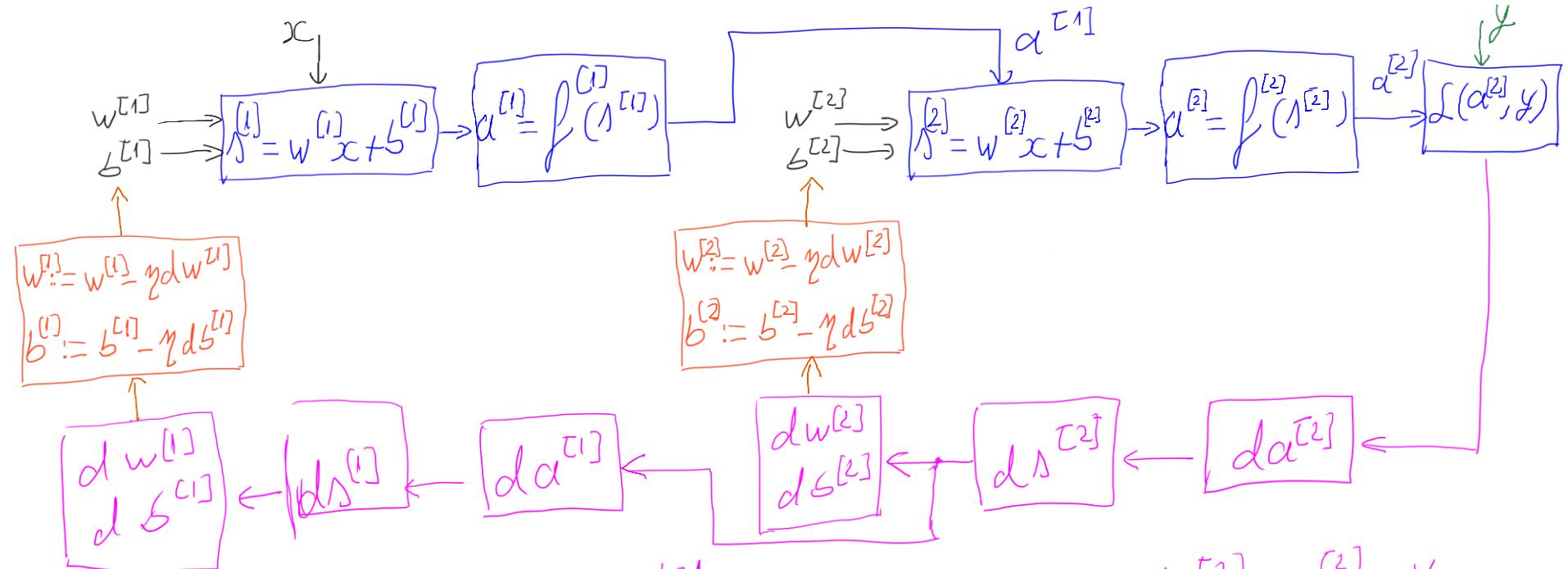
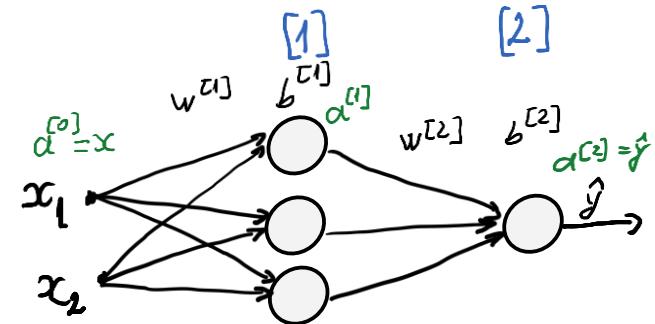


A neuron in the  $l^{\text{th}}$  layer

## 2-layer NN (2 inputs, 1 output).

1. Compute the output - Forward propagation
2. Compute the gradients – backward propagation
3. Update the parameters

## Training for 1 example



$$ds^{[1]} = w^{[2]T} \cdot ds^{[2]} * f'(s^{[1]})$$

$$\begin{cases} dw^{[1]} = ds^{[1]} \circ c^T \\ db^{[1]} = ds^{[1]} \end{cases}$$

elementwise multiplication

$$ds^{[2]} = a^{[2]} - y$$

$$\begin{cases} dw^{[2]} = ds^{[2]} a^{[1]T} \\ db^{[2]} = ds^{[2]} \end{cases}$$



## 2-layer NN (2 inputs, 1 output).

1. Compute the output - Forward propagation
2. Compute the gradients – backward propagation
3. Update the parameters

### Checking dimensions

$$w^{[2]}, dw^{[2]} \quad (n^{[2]}, n^{[1]}); (1, 3)$$

$$s^{[2]}, ds^{[2]} \quad (n^{[2]}, 1); (1, 1)$$

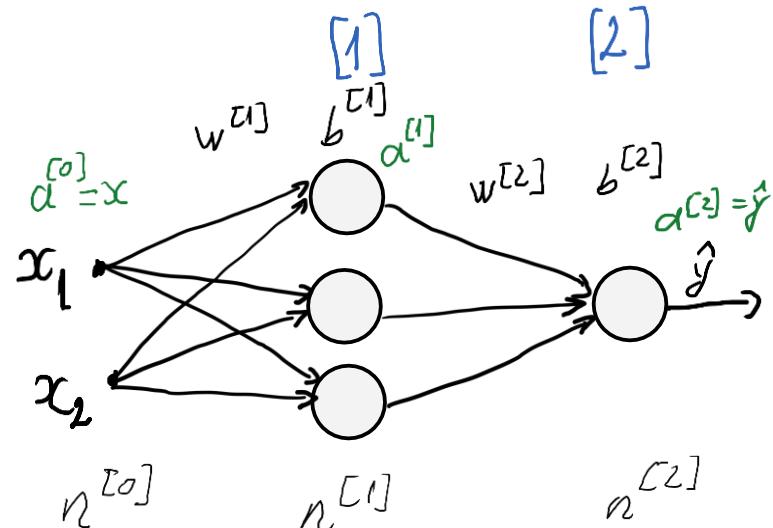
$$w^{[1]}, dw^{[1]} \quad (n^{[1]}, n^{[0]}); (3, 2)$$

$$s^{[1]}, ds^{[1]} \quad (n^{[1]}, 1); (3, 1)$$

$$ds^{[1]} = w^{[2]^\top} \cdot ds^{[2]} * f'(s^{[1]})$$

$$(n^{[1]}, 1) \quad \underbrace{(n^{[0]}, n^{[2]})}_{(n^{[1]}, 1)} \quad (n^{[2]}, 1) \quad (n^{[0]}, 1)$$

$$(n^{[1]}, 1)$$



## 2-layer NN (2 inputs, 1 output).

### Backward propagation (Compute the gradients )

#### Summary

1 example

$$dJ^{[2]} = a^{[2]} - y$$

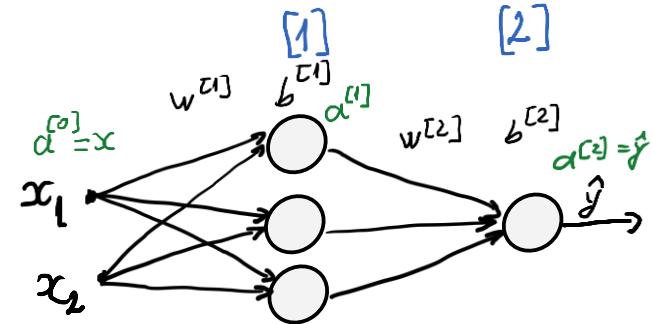
$$dW^{[2]} = dJ^{[2]} a^{[1]T}$$

$$d\theta^{[2]} = dJ^{[2]}$$

$$dS^{[1]} = w^{[2]T} \cdot dJ^{[2]} * f^{[1]}'(S^{[1]})$$

$$dW^{[1]} = dS^{[1]} x^T$$

$$d\theta^{[1]} = dS^{[1]}$$



$m$  examples       $J(w, b) = \frac{1}{m} \sum_{i=1}^m \mathcal{L}(a^{(i)}, y^{(i)})$

$$dS^{[2]} = A^{[2]} - Y$$

$$dW^{[2]} = \frac{1}{m} dS^{[2]} A^{[1]T}$$

$$d\theta^{[2]} = \frac{1}{m} np.sum(dS^{[2]}, axis=1, keepdims=True)$$

$$dS^{[1]} = W^{[2]T} dS^{[2]} * f^{[1]}'(S^{[1]})$$

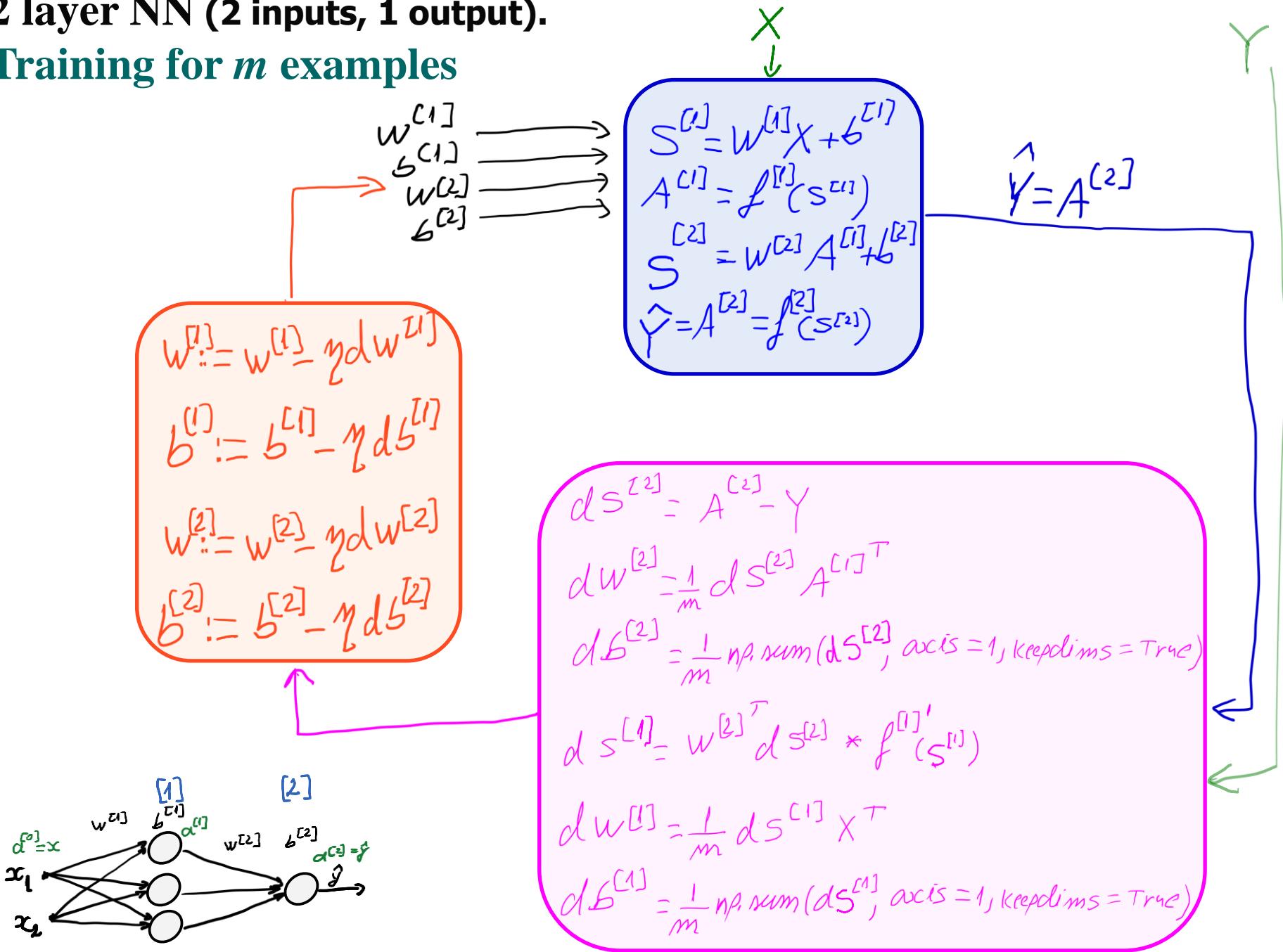
$$dW^{[1]} = \frac{1}{m} dS^{[1]} X^T$$

$$d\theta^{[1]} = \frac{1}{m} np.sum(dS^{[1]}, axis=1, keepdims=True)$$

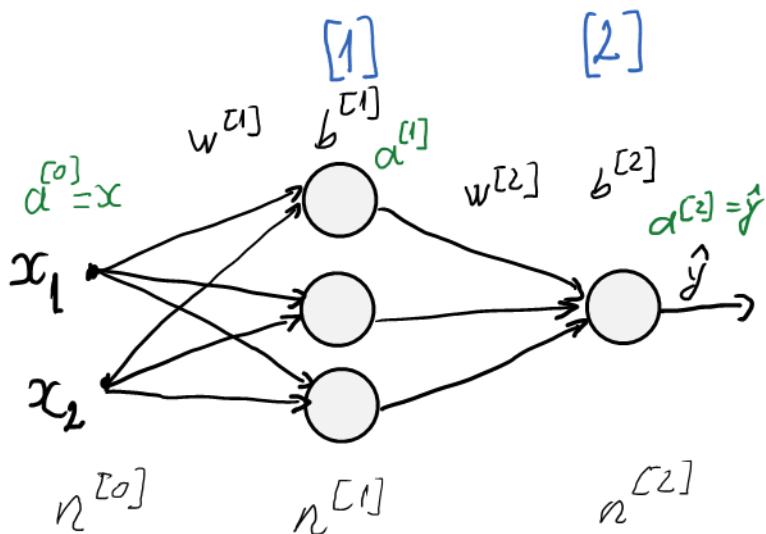


# 2 layer NN (2 inputs, 1 output).

## Training for $m$ examples



# Initialization of NN ( $W, b$ )

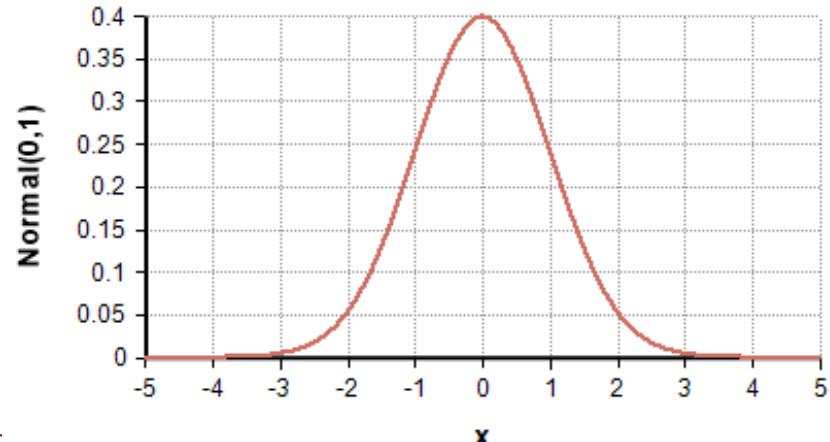


```
W[1] = np.random.randn(n[1], n[0]) * 0.01  
b[1] = np.zeros((n[1], 1))
```

```
W[2] = np.random.randn(n[2], n[1]) * 0.01  
b[2] = np.zeros((n[2], 1))
```

- ❖ It is recommended to initialize the weights matrices ( $W$ ) with small random values (not zero!)
  - ❖ For large values, the activation functions (sigmoid type) will be saturated – passive regions
  - ❖ If we are using zero for  $W$ , the gradient descent cannot evolve at all!
- The bias vectors can be initialized by 0.

*randn* generates an array, filled with random floats sampled from a univariate “normal” (Gaussian) distribution of mean 0 and variance 1.



# Methodology to build and train an ANN model

